# **Beam Instrumentation**

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## Beam Instrumentation Lecture 4

High Resolution Beam Position Monitor Cavity Beam Position Monitor (Cavity BPM)

- RF cavity based technology
- with nanometer resolution

# Introduction

**Basic Idea of Beam Measurement** 

Fundamental Relation of RF cavity

### **Concept of Cavity BPM**

#### Stripline BPM

- the position sensitive factor was defined by mechanical geometry
- zero position also produce the large signal for each electrode.
- large thermal noise for wide bandwidth ( a few 100MHz )

Difficult to get high resoultion

$$x = S_{\delta} \frac{V_1 - V_3}{V_1 + V_3} \qquad S_{\delta} = \frac{R}{2} \frac{\alpha}{\sin \alpha}$$

#### Cavity BPM

- position is calculated with the dipole mode of cavity pickup
- no signal at zero position
- samll thermal noise for narrow bandwidth ( a few MHz )

#### Possible to get high resolution

### TM110 mode for position measurement



# Monopole Mode ; Uniform to the transverse directionDipole Mode; No field at Center, 2 modes existsWe will use these modes for position measurement

### Q value of RF Cavity

 ${\it Q}$  value ( Loaded  ${\it Q}$  ); The decay rate of the stored energy

$$Q_L \equiv \frac{\omega U}{P}$$

 $Q_0$ ; energy loss by the thermal loss

- defined by the cavity material and the surface condition



Q value consists of two component  $Q_0$  and  $Q_{ext}$ .

Coupling Constant ( $\beta$ );  $\beta \equiv \frac{P_{out}}{P_{wall}} = \frac{Q_0}{Q_{ext}}$ The ratio of  $Q_0$  and  $Q_{ext}$ 

### *R/Q of RF Cavity*

R/Q; Relationship between the stored energy and electrical field

$$R/Q = \frac{|\int \vec{E} d\vec{s}|^2}{\omega U}$$

The interaction between beam and cavity is expressed with R/Q.

The excitation voltage by the beam is 
$$V_{exc} = rac{\omega}{2}(R/Q)q$$
  
Thereby, the beam induced energy is  $U = rac{V_{exc}^2}{\omega(R/Q)} = -rac{\omega}{4}(R/Q)q^2$ 

The pickup voltage also is expressed with R/Q.

The output power from the port is  $P_{out} = \frac{\omega U}{Q_{ext}} = \frac{\omega^2 q^2}{4Q_{ext}} (R/Q)$ Thereby, the output voltage is  $V_{out\,0} = \sqrt{ZP} = \frac{\omega q}{2} \sqrt{\frac{Z}{Q_{ext}}} (R/Q)$ 

The external Q is Qext, the impedance is Z for the port.

### Signal from the RF Cavity



Determined by the  $Q_L$ 

### *R/Q of the dipole mode of Pillbox Cavity*



Electric Field of the dipole mode is

$$E_z = E_0 \cos \phi J_1(rk) e^{i\omega t} \ k_{110} = \omega_{110}/c = rac{3.83}{b}$$

R/Q is calculated with its definition



$$R/Q(x) = \frac{|V|^2}{\omega U}$$

$$V(x) = \int_0^L E_z dz$$

$$U = \frac{1}{2} \int \epsilon_0 |E_z|^2 dV$$

$$R/Q = 50.5 \times (\frac{\omega}{c})^3 LT^2 \underline{x^2}$$

$$T = \frac{\sin \frac{\omega L}{2c}}{\frac{\omega L}{2c}}$$

$$R/Q \text{ of dipole mode}$$
is proportional to  $x^2$ 

### Beam Position Measurement by measuring the dipole mode

Back to the relation of the pickup voltage;

$$egin{aligned} V_{out\,0} &=& \sqrt{ZP} &=& rac{\omega q}{2} \sqrt{rac{Z}{Q_{ext}}(R/Q)} \ R/Q &= 50.5 imes (rac{\omega}{c})^3 LT^2 x^2 \end{aligned}$$

The pickup voltage is proportional to the position offset.

We can measure the beam position from the pickup voltage.

**Feature of the Pickup Signal** Effect of the finite bunch length



 $V_{total\ exc} = V_0 \int_{-\infty}^{\infty} \rho \cos\left(\frac{\omega z}{c}\right) = V_0 \exp\left(-\frac{\omega^2 \sigma_z^2}{2c^2}\right)$ 

The excitation voltage is weaker by suppressing each other for  $\sigma_z \ll c/\omega$ .

We shuold better to select lower RF frequency than bunch length.

### Feature of the Pickup Signal Effect of the beam angle



### **Feature of the Pickup Signal** Effect of the bunch tilt





The sensitivity of the bunch tilt is proportional to  $\sigma_{\tau}^2$ .

Small  $\sigma_{\tau}$  is better.

$$V_{-} = -A\frac{q}{2}\frac{\theta\sigma_{z}}{2}\sin(\omega(t-\sigma_{z}/c))$$
$$V_{tilt} = V_{+} + V_{-}$$
$$= \frac{Aq\theta\sigma_{z}}{2}\sin\left(\frac{\omega\sigma_{z}}{c}\right)\cos\omega t$$
$$\approx \frac{Aq\theta\omega\sigma_{z}^{2}}{2c}\underline{-\cos\omega t}$$

Oz q/2

 $V_{+} = A \frac{q}{2} \frac{\theta \sigma_z}{2} \sin(\omega (t + \sigma_z/c))$ 

Not only the amplitude, but also the phase detection is important to the measurement.

### Selection of the RF frequency and Cavity Length



Beam induced voltage of dipole mode is a function of

- bunch length
- frequency of dipole mode
- cavity gap
- 1) Cavity voltage is set to be 8 mm. (parameter of the accelerator)
- 2) Frequency is set to around 6GHz.
- 3) Cavity is as small as possible to reduce the effect of the beam angle.

### **Feature of the Pickup Signal** Effect of the tail of monopole mode

#### We must select the dipole frequency to separate the monopole mode.

| Mode | $f_0$    | $\mathbf{R}/\mathbf{Q} \ [\Omega]$ | $Q_L$ |
|------|----------|------------------------------------|-------|
| 010  | 4.03 GHz | 14300                              | 8000  |
| 020  | 9.25 GHz | 9880                               | 8000  |
| 110  | 6.43 GHz | $1.17 \times 10^{-12} (1nm)$       | 6000  |



Since the amplitude of monopole mode is huge to the dipole mode, the tail is affect to the dipole mode signal.

> -Bandpah filetr -Mode selectable coupler

### **Dipole Mode Selectable Coupler 1**



#### Magnetic coupling with slot shape hole

### **Dipole Mode Selectable Coupler 2**



In order to be mode cleaning, the coaxial cable is connected after the wave guide.

In order to minimize the electrical offset of the cavity, the diagonal 4 output ports are put to the cavity.

### **Design of the Coupling of the Pickup Port**



**S** ; proportional to the signal sensitivity of RF cavity

#### N; Thermal Noise

 $\approx kT f_{BW}$  $p_{TN}$  $V_{TN} \approx \sqrt{4kTZf_{BW}}$ Bandwidth is proportional to  $1/\tau$ .

### **Resolution Limit of the Cavity BPM**



$$NF_{total} = \underline{NF_1} + \frac{NF_2 - 1}{G_1} + \frac{NF_3 - 1}{G_1G_2} + \cdots$$

The first amp is the main noise source

### **RF** Cavity Beam Position Monitor for ATF2

tuner



### XY Isolation of the Dipole Mode Signal





tuhei

XY isolation is tune with the push-pull tuner by keeping the dipole frequency.





### **Offest Measuremnt**

Electrical offset with respect to mechanical offset is measured offline analysis.

Electrical offset is evaluated by measuring the offset from both side of mechanical reference.

> The mechanical offset (including machining error) was less than 10 µm.



### Measurement of the R/Q for the RF Cavity



# **Readout Electronics**

Introduction of two method

- 1) Homodyne Method (developing by KEK)
- 2) Heterodyne Method (developing by SLAC)

### **Readout Electronics of Cavity BPM** Frequency Conversion



Frequency is converted to useful frequency for the readout

$$A\sin(\omega_1 t + \underline{\phi_1}) \times B\sin(\omega_2 t + \phi_2) = \frac{AB}{2} [\cos((\omega_1 - \omega_2)t + (\underline{\phi_1} - \phi_2)) - \cos((\omega_1 + \omega_2)t + (\phi_1 + \phi_2))]$$

Converted signal keeps the phase information of the initial RF.

### **Readout Electronics of Cavity BPM** Homodyne Method





**Position information** is converted to the amplitude information



# **Readout Electronics of Cavity BPM**

Heterodyne Method



-Frequency is converted to lower frequency.
-Converted signal has phase and amplitude information.



IF power



### **Readout Electronics of Cavity BPM** Heterodyne Method (continued)



Down converted signal is fitted by readout software.

$$V = V_0 + Ae^{-\Gamma(t-t_0)} \sin(\omega(t-t_0) + \phi)$$
$$I_Y = \frac{A_Y}{A_{Ref}} \sin(\phi_Y - \phi_{Ref})$$
$$Q_Y = \frac{A_Y}{A_{Ref}} \cos(\phi_Y - \phi_{Ref})$$

Position information is converted to the amplitude information by the readout software.



### Characteristic Measurement with Beam Position Sensitivity Measurement



-Amplitude measurement with diode -Position was changed by beam steer -Calibrated with stripline BPM

#### The position sensitivity is consistent with the design value.

The position sensitivity should be evaluated by comparing other BPM signal, because the signal include the attenuation of the cable loss and so on .

### Characteristic Measurement with Beam Angle Sensitivity Measurement



Measured angle sensitivity 10nm / nrad Consistent with design

We can cancelled by using phase information.

### **Confirmation of XY Isolation**



XY isolation was confirmed by measuring Y signal, when beam has X offset.

offset in x 5mm, signal in Y-port < 50 μm < -40dB x-y isolation

Measure XY coupling was almost 40dB, consistent with the design.

### **Resolution Measurement**

Position resolution measurement is done with 3 BPMs



The position resolution is evaluated by comparing the masured BPM position and the evaluated position from another 2 BPM position.

$$X2(X1,X3) = \frac{X1+X3}{2}$$
$$\sigma(X2-X2(X1,X3)) = \sqrt{\sigma_{X2}^{2} + \frac{\sigma_{X1}^{2} + \sigma_{X3}^{2}}{4}} = \sqrt{\frac{3}{2}}\sigma_{X1}$$

### **Resolution Measurement**

We must stabilized the relative position of BPMs within nm level.

Setup of KEK cavity BPM



BPM position is stable by position feedback.

Setup of SLAC cavity BPM



BPM position is stable by using mechanical stable stage.

### **Achieved Resolution in ATF**

#### Readout electronics is Homodyne type electronics.



the position resolution is evaluated by comparing the Y2 signal and the Y2 value evaluated from BPM1 and BPM2 information.

 $Y2I = a_0 + a_{Y1I} \times Y1I + a_{Y3I} \times Y3I + a_{REF} \times REF$  $+a_{X1} \times X1 + a_{X3} \times X3 + a_{Y1Q} \times Y1Q + a_{Y3Q} \times Y3Q$  $+a_{Y1I^2} \times Y1I^2 + a_{Y3I^2} \times Y3I^2$ 

 $\Delta = Y2I - Y2I (Y1I, Y1Q, X1, Y3I, Y3Q, X3)$ 

### **Achieved Resolution in ATF** Continued ....



Calibration was done by changing the BPM2 position.

The 17.3nm resolution is achieved in ATF.

**Beam Test in ATF** 

5000

pulse number

6000

4000

1000

0

2000

3000

1 hour

### Some Comment of Cavity BPMs

The SLAC team achieved comparable resolution of the KEK team with Heterodyne method.

In present, by using high gain, small aperture type BPM, 5nm resolution is achieved with Homodyne method.

### Critical Performance Characteristics of Cavity BPM

-Dynamic range;

- We can select the dynamic range by putting the attenuator at the front of readout electronics.

 $(1mm - 100 \mu m for ATF2)$ 

-Resolution;

- Determined by the thermal noise.

(10nm for ATF2)

-Accuracy;

- We need online calibration for position sensitive factor.

- Electrical center is defined within 10µm to mechanical center.

- Time response is defined by cavity Q value.

-Large Impedance

- Used for transport line

- Possoble to use in the storage ring, but large impedance source.